Mukai Yu (Tom Notch)

Undergraduate · Passionate Roboticist · Integrative Systems and Design · Computer Science · Double Major

♥ HKUST, Kowloon, Hong Kong, China

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Education

m Carnegie Mellon University

MS IN ROBOTICS

Pittsburgh, PA, USA September 2024 - 2026

m Hong Kong University of Science and Technology

BSc in Integrative Systems and Design, Computer Science

• GPA: 3.62/4.30

m University of Illinois at Urbana-Champaign

Non-Degree Exchange in Computer Science

• GPA: 3.90/4.00

m Shenzhen Middle School

HIGH SCHOOL DIPLOMA

- Honor Curriculum
- Gaokao Track

Hong Kong, China

September 2019 - 2024

Urbana, IL, USA

January 2022 - May 2022

Shenzhen, Guangdong, China September 2016 - July 2019

Honors_____

2024 2022	HKSTP Tech FYP Sponsorship, Hong Kong Science and Technology Parks Reaching Out Award, HKSAR Government Scholarship Fund Shui On Innovation Fund Student Awards, Shui On Innovation Fund	100,000 HKD 10,000 HKD 10,000 HKD
2021	Dean's List (top 5%), HKUST	
2019	DJI RoboMaster Scholarship (top 10%), HKUST & DJI University Scholarship, HKUST	150,000 HKD 25,000 HKD

Publications _____

ACCEPTED

Andrew Jong, **Mukai Yu**, Devansh Dhrafani, Siva Kailas, Brady Moon, Katia Sycara, Sebastian Scherer. WIT-UAS: A Wildland-Fire Infrared Thermal Dataset to Detect Crew Assets from Aerial Views. *International Conference on Intelligent Robots and Systems (IROS)*, 2023

Experience _____

Huawei - Hong Kong Research Center - Design Automation Lab

Science Park, Hong Kong, China Sept 2023 - Jan 2024

SUPERVISOR: WILSON

- · Participate in software development of EDA netlist design verification via hardware emulation on processor cluster
- Related work: Parallel Bubble Scheduling and Allocation, Critical Path Fast Duplication, Parallel Genetic Algorithm

Carnegie Mellon University - The Robotics Institute - the AirLab

SUPERVISOR: PROFESSOR SEBASTIAN SCHERER

Pittsburgh, PA, U.S.A Jan 2023 - Aug 2023

- Publish IEEE IROS paper and release thermal image dataset for object detection
 - WIT-UAS: A Wildland-Fire Infrared Thermal Dataset to Detect Crew Assets from Aerial Views
- Lead hardware and perception algorithm development of the WildFire Project
- Redesign and manufacture Open Research Drone
- Develop and deploy SSD object detection deep learning model on NVIDIA Jetson Xavier with hardware acceleration

Carnegie Mellon University - The Robotics Institute

Pittsburgh, PA, U.S.A

May 2022 - Aug 2022

SUPERVISOR: DR. PENG YIN & DR. JI ZHANG

• Implemented **Online VIO System with Map Prior** on Boston Dynamics Spot

- Related work: VINS-Mono, FAST-LIO, Sequence SLAM, omnidirectional camera
- · Mastered ROS in 1 week

Hong Kong University of Science and Technology - Dept of CSE

Hong Kong, China May 2021 - Aug 2021

SUPERVISOR: PROFESSOR DAN XU

- Researched in real-time 3D reconstruction SLAM unsupervised deep learning algorithms
- Compared depth estimation results on different unannotated video datasets
- Reported algorithm summary of 10+ papers

Professional Experience ___

Shenzhen, China

Jan 2018 - Aug 2019

DJI Robomaster Robotics Summer/Winter Camp

RUNNER-UP TEAM 27

- Participated consecutively 4 cohorts: 2018 winter & summer, 2019 winter & summer
- Lead Embedded, Software, and Mechanical development, captain last time
- Built robots with Mecanum wheel Omnidirectional chassis and pneumatic actuator from scratch in 2 weeks

Extracurriculum ___

HKUST ENTERPRIZE Robomaster Robotics Team 20+

Hong Kong, China

SENIOR SOFTWARE ENGINEER

Sept 2019 - Feb 2020

- Built quaternion mathematical library for rigid transformation
- Implemented robust IMU complementary filter and stabilization Gimbal algorithm

Projects

BIPV Facade Mounting Robotics

Hong Kong, China

ROBOTICS SOFTWARE **LEAD** *5

Sept 2023 - May 2024

- Supervisor: Professor Chi Ying TSUI
- Robotic automatic mounting of PV(solar) panels on building facades
- Funded 100,000 HKD by HKSTP Tech FYP Sponsorship

WildFire ☑ HARDWARE AND PERCEPTION LEAD 2 10+

Pittsburgh, PA, U.S.A

Jan 2023 - Aug 2023

- Supervisor: Professor Sebastian Scherer
- Burning-time wildfire mapping and prediction system with UAV swarm
- Field-tested at real local prescribed fire sites with Pittsburgh Fire Department

Lighthouse ✓ (year-long project)

Hong Kong, China Sept 2020 - May 2021

CAPTAIN OF DEVELOPMENT TEAM 3

- Supervisor: Professor Ajay JONEJA
- Interactive & Intuitive Indoor Navigation System
- Built power-efficient signage unit with BLÉ, WiFi, and LCD panel
- Designed and deployed website for user interaction with signage unit
- · Private Github Repository available on demand

VAN€ 🗹 (year-long project)

CAPTAIN OF DEVELOPMENT TEAM 44

Hong Kong, China Sept 2020 - May 2021

- Supervisor: Professor Winnie Suk Wai LEUNG
- vision-based professional indoor workout assistant app
- Applied 3D pose estimation deep learning algorithm and online computation

Course Work

ELEC 5660 Introduction to Aerial Robotics

HKUST

PROJECT: GNN FOR SPARSE VISUAL FEATURE MATCHING

2024 Spring

• Topics: Rigid Body Transformation, Quaternion, Quadrotor Control, Trajectory Generation, Path Planning, Feature Detection & Matching, Optical Flow, Dense Stereo, Bayesian Inferencing, Extended & Augmented State EKF, Particle Filter, SLAM

COMP 5222 Advanced Machine Learning with Graphs

HKUST

PROJECT: GNN FOR SPARSE VISUAL FEATURE MATCHING

2023 Fall

Topics: Graph-based semi-supervised learning, Network embedding, Graph neural networks, Graph and subgraph isomorphism, Knowledge Graphs

COMP 6411B Advanced Topics in 2D and 3D Deep Visual Scene Understanding

HKUST

PROJECT: 3D RECONSTRUCTION FROM DEEP INFERENCE DEPTH

2022 Fall

 Topics: Semantic Segmentation, Depth Estimation, 2D/3D Object Detection, Multi-Task Learning, 3D Scene Reconstruction, Implicit Representation Learning, Visual SLAM

CS 498 Machine Perception

UIUC

A+ 2022 Spring

• Topics: SLAM, 3D reconstruction, Object Detection, Bayesian Filter

CS 446 Machine Learning

UIUC

A-

2022 Spring

• Topics: discriminative models, generative models, reinforcement learning models

CS 425 Distributed Systems

UIUC.

A-

2022 Spring

• Topics: distributed transactions, consensus, mutual exclusion, concurrency control

COMP 5411 Advanced Computer Graphics

HKUST

A-

2021 Fall

- Topics: 3D model representation & manipulation, rendering, GPU computing
- Rendering Project: Music Visualizer

Skills ____

Programming, C/C++ · Python (NumPy & PyTorch) · MATLAB · Javascript · HTML · CSS · GLSL **Software**, Ubuntu · ROS · Docker · Solidworks · Web Development · Mobile Applications · vSLAM **Language**, Mandarin Chinese (Native) · English (TOEFL: 104/120 with Speaking 28/30)

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